USER MANUAL

MINI BMS CENTRALIZED VERSION

MiniBMS is a battery management system designed for LiFePo4 cells, used in Electric Vehicles. MiniBMS is desi-ned to be reliable and cost effective solution; it has most basic functions, implemented via simple analog circuit and one wire interface, which also allows easy installation and troubleshooting. MiniBMS Features:

- Support for HiPower, ThunderSky, SkyEnergy and other LiFePo4 cells. Installs directly on cell terminals

  using included ring terminals. One terminal has rigid connection supporting BMS module, the other is connected via short wire. This design allows installation on virtually any cell size. BMS module is very small, 48mm x 30mm and fits easily on most prismatic cells.
- Optional support for centralized installation, with single board managing up to 16 cells. Useful for smaller cell sizes and packs, such as E-bikes, small cars, etc. Head end control board is integrated in the Master board. Slave boards only have cell modules.
- Low profile Printed Circuit Boards with Surface Mount Components allows installation in tight spaces, inside battery boxes, etc. Components are sealed from dirt and moisture, safe to install under the hood of the car.
- Single wire Normally Closed (NC) analog communication loop. All modules connect in a single series string using automotive style Quick Disconnect crimp terminals. NC loop is extra reliable since it senses loose wiring connections as well as low and high cell conditions. Analog NC loop is not affected by high electrical noise inside EV, which has severe negative effects on digital communications.
- Less than 10 mA operating current to prevent bleeding cells over long time period when not in daily use. Resistors protect every part of the circuit from potential semiconductor failures. Any component failure results in BMS alerts, protecting the battery even from BMS itself.
- PTC resettable fuse protects from overheating during shunting as well as short circuit conditions. Fuse opens if temp reaches 80C or if shunting current reaches 1 Amp. Open fuse results in same alert as full charge, shutting down the charger. Fuse returns to normal conditions automatically.
- High Voltage Cutoff (HVC). HVC voltage level is selectable at the time of purchase for most popular cell types. When first cell reaches HVC it will cause BMS to shut down the charger, effectively protecting your battery pack. Since BMS can control AC power to the charger, you can use practically any charger with this BMS, even "dumb" chargers without special LiFePo4 charging profiles. This requires purchase of high current solid state AC relay, not included with BMS. If your charger has BMS shutoff input, then you don't need AC relay. This datasheet is an example of such AC relay http://www.teledynerelays.com/pdf/industrial/sh.pdf . You can find man others from various online electronic parts retailers, including Ebay. Make sure you get a relay rated for higher continuous currents than your charger pulls from AC outlet, so it doesn't get too hot. Still, you may need to mount it on a heat sink if it gets hot.
- Low Voltage Cutoff (LVC) is temperature compensated. Each module has a thermistor which automatically justs LVC for each cell, which works well if some cells are installed in different locations in the car with different temperatures at each location. LVC is set to 2.5V at 0C temp, 2.6V at 25C temp and 2.7V at 50C temp, linearly adjusting itself across the entire temp range.
- Green LED on each cell module indicates normal conditions, i.e. cell voltage is between LVC and HVC levels. All cells must have Green LEDs on during normal use. When any cell goes below LVC or above HVC levels, Green LED turns off and alert is created by open NC loop.
- Optional shunt balancing has a maximum shunting current of 0.75 Amp. Red LED comes on during shunting for visual indication. Shunting slows down charging process on cells reaching HVC sooner than other cells, allowing other cells to catch up. This is referred to as "top balancing". Initial manual balancing is recommended, so BMS can keep the pack balanced long term.
- Head end control board is an interface between cell modules and charger and motor controller. It uses simpl NO/NC connections to act on LVC and HVC events. Control board senses alerts from NC loop and acts on those by reducing the throttle (LVC) and shutting down the charger (HVC). Simple interface allows compatibility with virtually any charger and motor controller. In centralized version of MiniBMS, head end board is integrated with Master board.
- Head end control board supports piezo Buzzer to provide audible alarm for the driver when alerts are triggered by cell modules. Any 12V low current buzzer from Radio Shack can be used.

Description of MiniBMS boards:

Master Board. Each MiniBMS system must have one Master Board, this board integrates head end control module, including relays and the buzzer, in addition to managing up to 16 cells. Full Master board has 16 cell modules. If your pack size requires one partial board (pack size not divisible by 16), then you must get partial Master board, with 12, 8, or 4 modules. For example, if your pack has 40 cells, you need one partial Master board (8 cells), and 2 Slave boards (16 cells each). Slave Board. If your pack has more than 16 cells, then you also need one or more Slave Boards. Slave board only has 16 cell modules. Slave boards cannot be partial. Boards arrangement. Single BMS system can be arranged in one stack or multiple stacks. Remote stack can be useful if your pack is broken into multiple battery boxes, some in the front and some in the back of your EV. Then, you can make a stack of BMS boards at the front battery box and remote stack at the rear battery box, and only use 2 wires to connect 2 stacks together. Each board has 3 jumpers, which set the role of each board. Bottom board in each stack must have a "Bottom" jumper installed. If entire system is in one stack and there are no remote stacks, then "No Slave" jumper must be installed on Master Board only. "Top Slave" jumper is only installed on top board of remote stack. Middle boards have no jumpers at all. Each board has board-to-board connections in 4 corners, so one board plugs into the next board. Two adjacent boards must be shifted 0.1" to match connections. When mating more than 2 boards, shift them in a zigzag pattern to make vertical column. Once you stack all boards, thread cable ties thru all holes in each corner to tie all boards together, so they don't pull apart from vibration.

List of all possible roles:

- Master Board only (16 cell pack or less). This will be the only board in the system. Jumpers "Bottom" and "No Slave" must be installed.
- Master Board in a single stack. This will be a top board in the stack of multiple boards. Jumper "No Slave" must be installed since there is no remote stack of slave boards.
- Bottom Slave board. This will be the bottom board in each stack. "Bottom" jumper must be installed.
- Middle Slave board. These boards have no jumpers installed.
- Master Board in a multi-stack system. This will be a top board in a Master stack. This board will have no jumper Slave Loop wires will run to the Top Slave board in remote stack, to complete single signaling loop.
- Top Slave board in remote stack. This will be the top board in the remote stack of Slave boards. Slave Loop wires from this board will run to Slave Loop wires on the Master Board, making a single signaling loop across multiple stacks on boards. "Top Slave" jumper must be installed.

MiniBMS Installation:

CRITICAL WARNING: Make sure your battery pack is physically disconnected from the rest of your EV when attaching BMS modules to your cells. Failure to do so may result in last BMS module completing the high voltage circuit before
it gets attached to the last cell terminal. This will damage the BMS module beyond repair and will not be covered by warranty!!!

1. Depending on the size of your battery pack you may need one or more Slave Boards in addition to the Master Board. If your pack size is not divisible by 16, then your Master Board will have less than 16 modules. Identify all your boards based on descriptions on the page above and make sure proper jumpers are installed where needed. Cell count starts from most negative cell in the pack. Cell count starts from the Bottom board. C1 on the Bottom board refers to most negative cell in the pack. C16 on the Bottom board refers to cell 16 in the pack. C1 on the 2nd board from the bottom refers to cell 17 in the pack, and so on. "C1-" wire on the bottom board comes from negative terminal of most negative cell. "C1-" is not used on any other boards except the Bottom board, since "C16+" from previous board is connected to "C1-" on the next board via board-to-board connections.
2. Wire all leads from cells to BMS boards, starting with most negative "C1-", then "C1+", then "C2+", then "C3+", and so forth. Use small flat screwdriver with isolated handle and be careful not to touch any live leads with your hands. Green LEDs will light up for each cell as you connect them. CORRECT SEQUENCE IS CRITICAL TO AVOID DAMAGE TO BMS BOARDS AND YOUR CELLS!!!

3. Alternatively, you can wire all cell leads to BMS board before connecting them to your cells. This might be easier and safer route, but you must carefully identify each wire to ensure proper sequence and make sure ring terminals at the end of each wire do not touch anything, wrap each ring terminal in some insulating material and take it off just before installing it on the cell terminal.

4. Once all cell leads are installed, carefully stack boards if you have more than one board. At this time all Green LEDs must be lit, indicating correct installation. There should be no Red LEDs lit at this time. You may want to place electrical tape on top of wire terminals on each board to protect it from touching the next board in the stack.

5. Wire head end control board according to attached schematics. B+ terminal must come directly from the 12V aux battery to ensure BMS is powered while ignition is off during charging. Ignition input is required to reset BMS after each charge. When wiring to charger and motor controller, please find most appropriate diagram for your type of charger and throttle assembly. If you are not sure which diagram is best for you, contact MiniBMS support and provide models of your charger, controller and throttle assembly to get detailed wiring directions.

6. Master Board has a buzzer installed. If your BMS is located such that the driver can't hear the buzzer from the board, then you must install additional remote buzzer. You can use any 12v low current Buzzer from Radio Shack or other retailers. The more annoying it is the more inclined the driver will be to react on LVC alerts, but it should not be deafening so the driver can pay attention to the road. Buzzer current should not exceed 250 mA, otherwise it will trip the fuse on the control board. Mount the buzzer under the dash board or under the steering wheel, so it can be heard clearly by the driver.

7. To test head end control board after it's been wired, remove "No Slave" jumper from the Master board, simulating BMS alert condition. This should result in buzzer coming on after 2-4 second delay. Delay is adjustable via trimpot on the head end control board. Delay is designed to filter out false LVC alerts during brief voltage sags which are normal during hard accelerations. When jumper connection is restored, buzzer should turn off immediately. It is not recommended to set delay more than 4 seconds to prevent deep discharge during LVC events.

8. To test charger connection to BMS, after all charger connections are made, turn on the charger and make sure it starts charging the pack normally. Ignition must be off at this time, so BMS can expect HVC signal. Manually break signaling Loop by removing "No Slave" jumper. After 2-4 second delay charger should turn off. When you restore NC Loop connection charger should remain in off state until you cycle ignition key on and off.

9. It's a bit more difficult to test BMS connection to motor controller since it requires running motor to observe throttle reduction. If your EV is drivable, you can arrange to interrupt NC wire loop from the cabin, using a temporary switch in line with NC wire loop to simulate LVC event. After 2-4 second delay you should observe throttle reduction and buzzer alert. In real LVC event throttle reduction will prolong your battery life so you can get off the road safely and prevent damage to your battery pack.

MiniBMS Operation:

1. During charging Ignition key is off, which tells BMS to expect HVC event. When first cell reaches HVC voltage BMS will interrupt NC loop and cause charger AC relay to interrupt power to the charger. HVC event will latch on, so charger will not come back on when resting voltage goes below HVC. NOTE: In ideal world HVC function may not even interfere with the charger, allowing it to finish CC/CV charging phases as intended by charger's manufacturer. However, in case there enough misbalance across multiple cells such that one cell gets to HVC much sooner than others, HVC will protect the cell by cutting off charging process prematurely. It is up to you what action to take depending on how prematurely HVC cutoff occurs. If charger is interrupted only a few minutes before the end of CV phase, at which point charging current is very low, then you are not losing much and you can simply let this happen every day. If you have BMS with shunting option, then shunting process will over time pull back this pesky cell and equalize it with others. Or, you can manually attempt to discharge that cell a little bit, to bring it down in line with others. You have many choices and MiniBMS is here to protect your battery investment, even at the cost of somewhat incomplete charge. You may soon realize that small amounts of charge at the end of the charge cycle are not all that important and not worth risking overcharge of individual cell.

2. You must disconnect the charger before turning Ignition on. Once ignition key is on, BMS will reset HVC

circuit to prepare it for the next charging cycle.

3. Once Ignition key is on BMS expects LVC events. During driving when your pack gets close to low charge levels BMS will sense LVC events from cells with smallest capacity. This will initially happen during heavy acceleration due to deeper voltage sag. 2-4 second delay is designed to filter out brief voltage sags which may happen while there is still plenty of charge in the pack. However, as you get closer to empty pack, LVC events will become more frequent and prolonged, which is an indication to the driver to get off the road ASAP. If LVC alerts become solid with little or no throttle applied, you have reached the lowest charge level and should not drive anymore. It's possible that one or two cells are damaged or have significantly lower capacity than others, causing LVC alerts when you don't expect them. Check Green LEDs on all BMS modules to find offending cells, which will have Green LED turned off during LVC event.

4. In a rare event when LVC alert is on solid you must keep the Ignition key on while turning on the charger. This is necessary to prevent charger relay from false tripping since it can't distinguish LVC event from HVC event. Within few minutes all cells will climb over LVC voltage and you can turn off ignition key and charger will remain running. This situation is an extreme case and should never be experienced unless you ignore LVC alerts and run your pack to empty. DO NOT leave the Ignition key on unattended while charging; it will disable BMS ability to turn off the charger when first cell reaches HVC level.
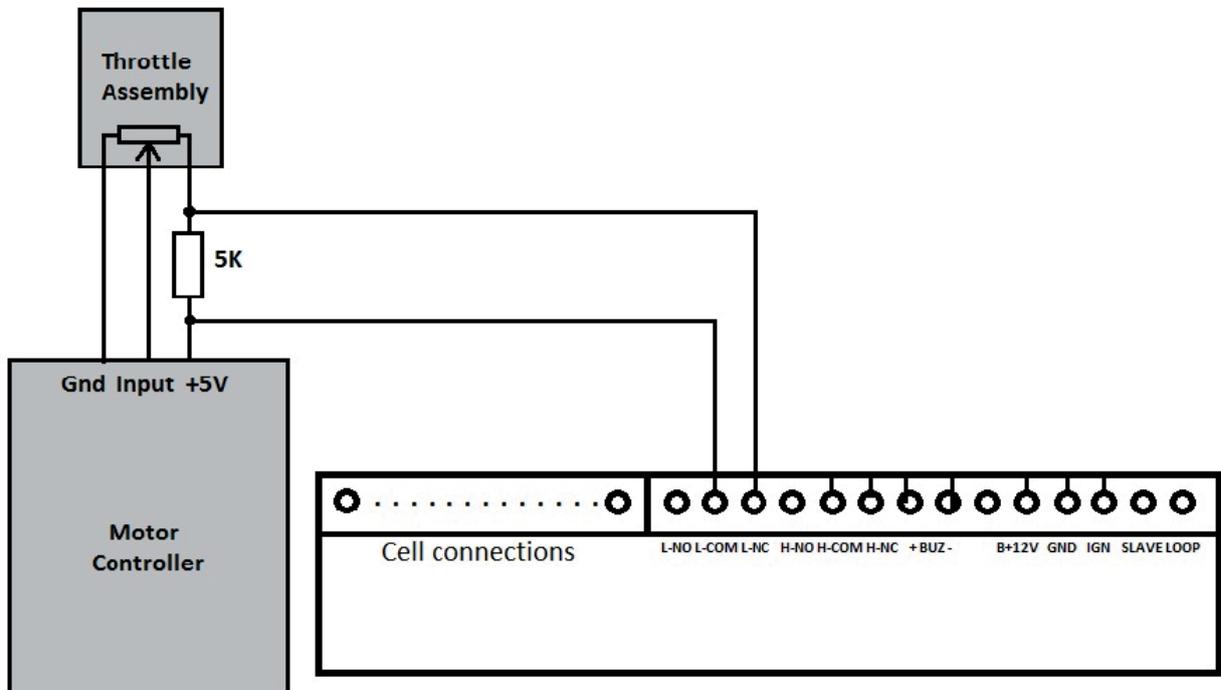
MiniBMS Wiring Diagram:

This basic diagram shows how to interface MiniBMS with your battery pack, charger and motor controller. This diagram shows motor controller with 2 wire resistive 0-5K pot box, which is common for Curtis, Logisystems and some other controllers. 5K resistor shown in the diagram will be connected in parallel to the pot box during LVC event, which will reduce total resistance to 2.5K, which effectively clamps the throttle to 50% of max throttle. You can manipulate resistor value if you wish to clamp LVC throttle to higher or lower levels. Keep in mind that getting off road safely should be higher priority than saving few battery cells, don't clamp the throttle too much so the car can keep driving at lower speeds.
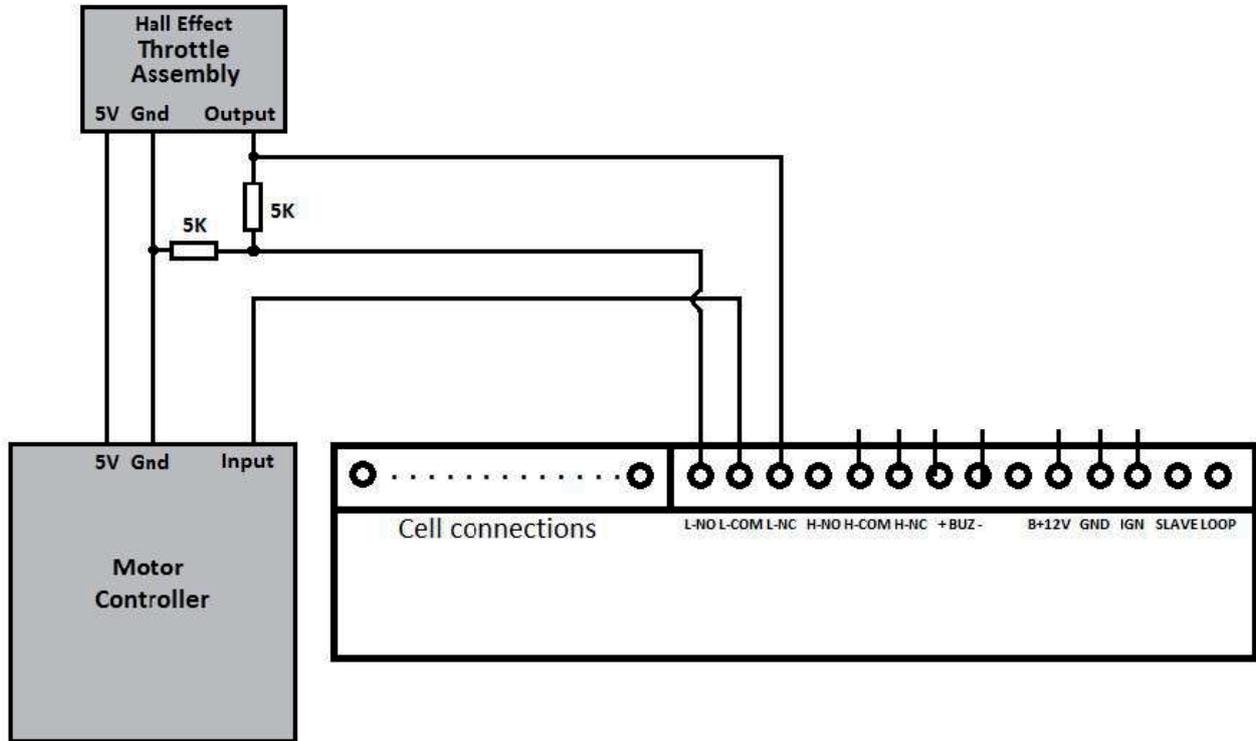

MiniBMS Wiring Diagram
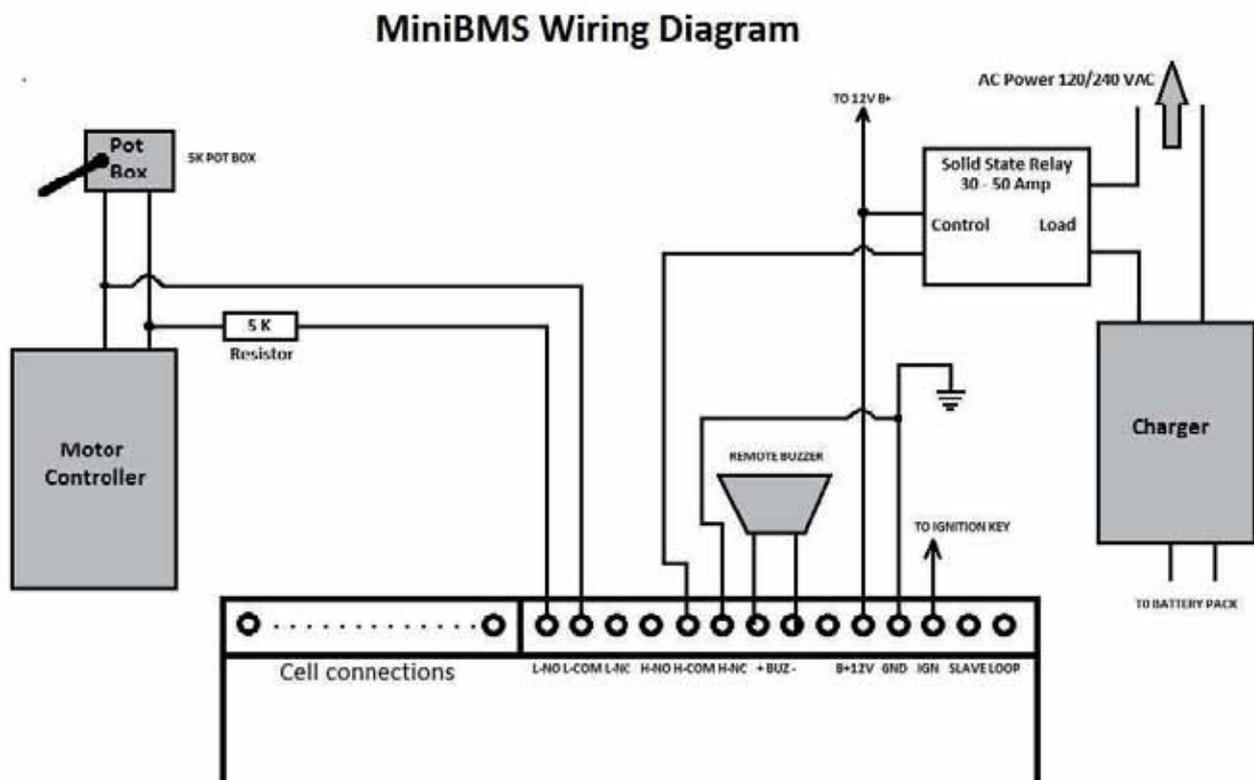
Next diagram shows only motor controller portion of MiniBMS wiring diagram for 3 wire resistive pot box and controller which expects 0-5V throttle input. Controllers which use this type of throttle input are Soliton1, Kelly, and others. Check controller's documentation for details. Do not use this diagram with Hall Effect throttles, please refer to the following diagram for Hall Effect throttles.

If you are not sure which diagram works best for your conversion, please contact MiniBMS support for assistance.

Next diagram shows only motor controller portion of MiniBMS wiring diagram for 3 wire Hall Effect throttle. Since Hall Effect device is powered by 5V input, we must use voltage divider on the output side of the throttle to reduce its output level during LVC event.

Hall Effect Throttle Assembly

5V Gnd Output

5K

5K

Motor Controller

5V Gnd Input

Cell connections

L-NO L-COM L-NC H-NO H-COM H-NC + BUZ - B+12V GND IGN SLAVE LOOP

Optional charger controls: Some chargers have BMS input functions, which turn off the charger based on ON/OFF or specific voltage input. You can wire such charger to MiniBMS control board without using high power solid state AC relay. Please note that control board NO/NC output has 2 Amp commutation current limits, if you exceed it you may damage the relay. Please check with MiniBMS support if you are not sure about this option. See additional diagrams below for optional charger interface.

Auxillary 12V battery note: MiniBMS relies on constant power supplied from your 12V aux battery. Please make sure your 12V battery is properly charged at all times to ensure correct BMS operation. For safety reasons MiniBMS will shut off the charging process if it loses 12V power to the head end control board, which may leave you with undercharged pack unexpectedly. MiniBMS takes less than 50 mA from 12V battery,
likely less than self discharge rate of typical Lead Acid battery, but any failure of the 12V battery will result in BMS triggering HVC event, so your traction pack will still be protected from potential overcharge, even at the cost of premature charger interruption.

LVC safety note: MiniBMS is designed to protect your battery pack from premature damage due to overcharge and over discharge. Specifically LVC function is carefully designed not to interfere with normal driving conditions until there is very little energy left in the pack. You should not let your pack get to LVC alerts on regular basis and you should not rely on LVC alone to gauge your pack State Of Charge. Using additional SoC instrumentation, such as voltmeter or special SoC gauge is highly recommended to avoid reaching LVC levels on regular basis. Know your range limitations and plan your route, LVC is there to protect your battery, even at the cost of leaving you stranded on the road. First LVC alerts will come under heavy acceleration and indicate that you only have few minutes left to drive until your pack is empty.

Additional wiring diagrams for popular chargers with BMS Input. Please note that not all Elcon (a.k.a. Chinoz) chargers have the BMS input. You would know about BMS input since you can't use the charger unless you apply control voltage on red/black wires.
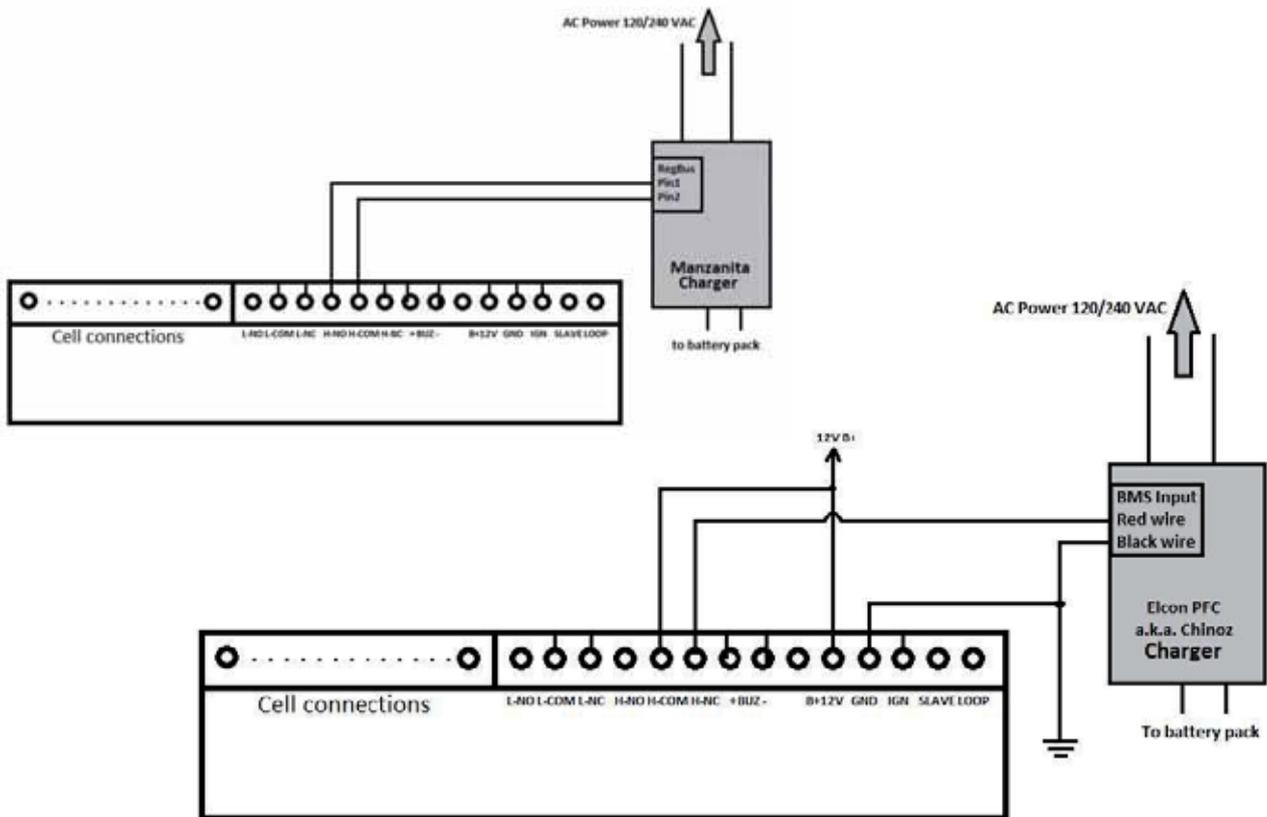
Below diagram shows how to connect cells to multiple boards. Note that C1- terminal is only used on Bottom Slave board and not connected on other boards.